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$$D) \left(\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 2 & 1 & 1 & 0 \\ 1 & -2 & s & 0 \\ 3 & s & t & 0 \end{array} \right) \sim \left(\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 0 & 3 & -1 & 0 \\ 0 & -1 & s-1 & 0 \\ 0 & 3+s & t-3 & 0 \end{array} \right)$$

$$\left(\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 0 & 1 & 1-s & 0 \\ 0 & 3 & -1 & 0 \\ 0 & s+3 & t-3 & 0 \end{array} \right) \sim \left(\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 0 & 1 & 1-s & 0 \\ 0 & 0 & 3s-4 & 0 \\ 0 & 0 & s^2+2s+t-6 & 0 \end{array} \right)$$

$$(-s-3)(1-s) = -s + s^2 - 3 + 3s$$

$$s^2 + 2s - 3 + t - 3$$

$$s^2 + 2s + t - 6$$

y $3s - 4 = 0 \Leftrightarrow s = \frac{4}{3}$ and $s^2 + 2s + t - 6 = 0$

$$\Leftrightarrow s = \frac{4}{3} \quad \& \quad \frac{16}{9} + \frac{8}{3} + t - 6 = 0 \Leftrightarrow t = 6 - \frac{16}{9} - \frac{8}{3}$$

$$= \frac{54 - 16 - 24}{9}$$

$$= \frac{14}{9}$$

we have nontrivial solutions.



Problem 2 Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation.

a (10 points) Prove that T is one-to-one if and only if $\text{Nul}(T)$ is trivial, i.e., $\text{Nul}(T) = \{\mathbf{0}\}$.

\Rightarrow If T is 1-to-1, $\forall \mathbf{x} \in \text{Nul}(T)$, $T\mathbf{x} = \mathbf{0} = T\mathbf{0}$

$\Rightarrow \mathbf{x} = \mathbf{0}$ because T is 1-to-1 $\Rightarrow \text{Nul}(T) \subseteq \{\mathbf{0}\}$

But $\mathbf{0} \in \text{Nul}(T) = \{\mathbf{0}\} \subseteq \text{Nul}(T) \hookrightarrow \text{Nul}(T) = \{\mathbf{0}\}$

\Leftarrow If $\text{Nul}(T) = \{\mathbf{0}\}$, $\forall \mathbf{x}_1, \mathbf{x}_2 \in \mathbb{R}^n$

$T(\mathbf{x}_1) = T(\mathbf{x}_2) \Rightarrow T(\mathbf{x}_1 - \mathbf{x}_2) = \mathbf{0} \Rightarrow$

$T(\mathbf{x}_1 - \mathbf{x}_2) = \mathbf{0} \Rightarrow \mathbf{x}_1 - \mathbf{x}_2 \in \text{Nul}(T)$

but $\text{Nul}(T) = \{\mathbf{0}\} \hookrightarrow \mathbf{x}_1 - \mathbf{x}_2 = \mathbf{0}$

$\therefore \mathbf{x}_1 = \mathbf{x}_2 \Rightarrow T$ is 1-to-1. \square

b (10 points) Show that the range (image) of T is a subspace of \mathbb{R}^m .

1) $T(\mathbf{0}) = \mathbf{0} \Rightarrow \mathbf{0} \in \text{Ran}(T) \subseteq \mathbb{R}^m$

2) Let $\mathbf{y}_1, \mathbf{y}_2 \in \text{Ran}(T) \Rightarrow \exists \mathbf{x}_1, \mathbf{x}_2 \in \mathbb{R}^n$

$T(\mathbf{x}_1) = \mathbf{y}_1, T(\mathbf{x}_2) = \mathbf{y}_2 \hookrightarrow \mathbf{y}_1 + \mathbf{y}_2 = T(\mathbf{x}_1) + T(\mathbf{x}_2)$
 $= T(\mathbf{x}_1 + \mathbf{x}_2)$

$\therefore \mathbf{y}_1 + \mathbf{y}_2 \in \text{Ran}(T)$

3) Let $\alpha \in \mathbb{R}, \mathbf{y} \in \text{Ran}(T) \Rightarrow \exists \mathbf{x} \in \mathbb{R}^n, T(\mathbf{x}) = \mathbf{y}$

$\Rightarrow \alpha \mathbf{y} = \alpha T(\mathbf{x}) = T(\alpha \mathbf{x}) \Rightarrow \alpha \mathbf{y} \in \text{Ran}(T)$

①, ②, ③ $\Rightarrow \text{Ran}(T)$ is a subspace of \mathbb{R}^m .

3)
 a) $3 \left\{ \begin{pmatrix} \text{Row 2} \\ \vdots \\ n \end{pmatrix} \rightarrow \boxed{2 \cdot \text{Row 1} + \text{Row 2}} \right.$

$n = 1$
 $E: \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \rightarrow \begin{pmatrix} x_1 \\ 2x_1 + x_2 \\ x_3 \end{pmatrix}$



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E is linear since

$$E(x+y) = E\begin{pmatrix} x_1 + y_1 \\ x_2 + y_2 \\ x_3 + y_3 \end{pmatrix}$$

$$= \begin{pmatrix} x_1 + y_1 \\ 2x_1 + 2y_1 + x_2 + y_2 \\ x_3 + y_3 \end{pmatrix} = E(x) + E(y). \quad E(\alpha x) = E\begin{pmatrix} \alpha x_1 \\ \alpha x_2 \\ \alpha x_3 \end{pmatrix}$$

$$= \begin{pmatrix} \alpha x_1 \\ 2\alpha x_1 + \alpha x_2 \\ \alpha x_3 \end{pmatrix} = \alpha \cdot E(x)$$

b) $E(x) = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot x$

c) $E^{-1} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_1 \\ -2x_1 + x_2 \\ x_3 \end{pmatrix}$

4) $A = \begin{pmatrix} -1 & 2 & a \\ 2 & -4 & -1 \\ 3 & 0 & 2a \end{pmatrix} \sim \begin{pmatrix} -1 & 2 & a \\ 0 & 0 & 2a-1 \\ 0 & 6 & 8a \end{pmatrix}$

$\sim \begin{pmatrix} -1 & 2 & a \\ 0 & 0 & 2a-1 \\ 0 & 6 & 8a \end{pmatrix}$





$$\sim \begin{pmatrix} -1 & 2 & a \\ 0 & 6 & 8a \\ 0 & 0 & 2a-1 \end{pmatrix}$$

If $2a-1 \neq 0$, A is invertible since
it is reducible to $\text{Id}^{3 \times 3}$.

$$\text{So } a \neq \frac{1}{2}$$

b) $a=0$

$$\left(\begin{array}{ccc|ccc} -1 & 2 & 0 & 1 & 0 & 0 \\ 2 & -4 & -1 & 0 & 1 & 0 \\ 3 & 0 & 0 & 0 & 0 & 1 \end{array} \right)$$

$$\sim \left(\begin{array}{ccc|ccc} 1 & -2 & 0 & -1 & 0 & 0 \\ 2 & -4 & -1 & 0 & 1 & 0 \\ 3 & 0 & 0 & 0 & 0 & 1 \end{array} \right) \sim \left(\begin{array}{ccc|ccc} 1 & -2 & 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 2 & 1 & 0 \\ 0 & 6 & 0 & 3 & 0 & 1 \end{array} \right)$$

$$\sim \left(\begin{array}{ccc|ccc} 1 & -2 & 0 & -1 & 0 & 0 \\ 0 & 1 & 0 & \frac{1}{6} & 0 & \frac{1}{6} \\ 0 & 0 & -1 & 2 & 1 & 0 \end{array} \right) \sim \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 0 & \frac{1}{6} \\ 0 & 1 & 0 & \frac{3}{6} & 0 & \frac{1}{6} \\ 0 & 0 & 1 & -2 & -1 & 0 \end{array} \right)$$



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$$A^{-1} = \frac{1}{6} \begin{pmatrix} 0 & 0 & 2 \\ 3 & 0 & 1 \\ -12 & -6 & 0 \end{pmatrix}$$

5) $T\left(\begin{pmatrix} x \\ y \\ z \\ t \end{pmatrix}\right) = \begin{pmatrix} 2x+y \\ z \\ x+z+t \end{pmatrix} \quad T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$

$$T(x) = \begin{pmatrix} 2 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix} \cdot x$$

$$\sim \left(\begin{array}{cccc|c} 2 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 \end{array} \right) \sim \left(\begin{array}{cccc|c} 1 & \frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & -\frac{1}{2} & 1 & 1 & 0 \end{array} \right)$$

$$\sim \left(\begin{array}{cccc|c} 1 & \frac{1}{2} & 0 & 0 & 0 \\ 0 & 1 & -2 & -2 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{array} \right) \sim \left(\begin{array}{cccc|c} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & -2 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{array} \right)$$



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$$\begin{aligned}x &= -t \\y &= 2t \\z &= 0\end{aligned}\quad \begin{pmatrix}x \\y \\z \\t\end{pmatrix} = t \begin{pmatrix}-1 \\2 \\0 \\1\end{pmatrix}$$

So $\text{Null}(T) = \text{Span} \left\{ \begin{pmatrix}1 \\2 \\0 \\1\end{pmatrix} \right\}$

b) $A = \begin{pmatrix}2 & 1 & 0 & 0 \\0 & 0 & 1 & 0 \\1 & 0 & 1 & 1\end{pmatrix}$

c) $A^T = \begin{pmatrix}2 & 0 & 1 \\1 & 0 & 0 \\0 & 1 & 1 \\0 & 0 & 1\end{pmatrix} \quad S(x) = A^T \cdot x$

$$\begin{pmatrix}2 & 0 & 1 \\1 & 0 & 0 \\0 & 1 & 1 \\0 & 0 & 1\end{pmatrix} \sim \begin{pmatrix}1 & 0 & 0 \\2 & 0 & 1 \\0 & 1 & 1 \\0 & 0 & 1\end{pmatrix} \sim \begin{pmatrix}1 & 0 & 0 \\0 & 0 & 1 \\0 & 1 & 1 \\0 & 0 & 0\end{pmatrix}$$

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$$\sim \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

All columns are lin. ind. So a basis of $\text{Col}(A^T)$

$$= \left\{ \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} \right\}$$

d) S is 1-1 since A^T is reduced to

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

which has a pivot in each column.
So no free variables in the
solution of $A^T x = 0$.

So the only solution is $x = 0$

