

# MATH107: Solutions to Final Exam problems

## Problem 1

1.a (5 points) Explain the difference between a sequence of numbers and a series of numbers and give the definition of a convergent series.

A sequence of numbers is a function  $s: \mathbb{N}^+ \rightarrow \mathbb{R}$  that can be represented by an ordered infinite list of its values  $s(n)$  that we label as  $s_n$ , i.e., write as  $\{s_n\}$ . A series  $\sum_{n=1}^{\infty} s_n$  is a formal sum of the terms of a sequence  $\{s_n\}$  that correspond to the sequence of partial sums of  $\{s_n\}$ , i.e.,  $\{S_n\}$  where  $S_n := s_1 + s_2 + \dots + s_n$ .

$\sum_{n=1}^{\infty} s_n$  is said to be convergent if  $\{S_n\}$  converges.

1.b (5 points) Give the definition of the harmonic series, and use the integral test to determine if it converges or not.

Harmonic series :  $= \left\{ \frac{1}{n} \right\}$

Let  $f: [1, \infty) \rightarrow \mathbb{R}$  be the function  $f(x) := \frac{1}{x}$   
so that  $\frac{1}{n} = f(n)$ .

Because  $\int_1^{\infty} f(x) dx = \int_1^{\infty} \frac{dx}{x} = \lim_{N \rightarrow \infty} \ln(N) - \ln(1) = \infty$ ,

the integral test implies that  $\left\{ \frac{1}{n} \right\}$  diverges.

**Problem 2** Let  $f(x) := \int_0^x \frac{1-e^{-t^4}}{t^2} dt.$

2.a (5 points) Obtain the Maclaurin series for  $f$ .

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!}$$

$$\begin{aligned} \Rightarrow e^{-x^4} &= \sum_{n=0}^{\infty} \frac{(-1)^n x^{4n}}{n!} = 1 - x^4 + \frac{x^8}{2!} - \frac{x^{12}}{3!} + \dots \\ \Rightarrow \frac{1-e^{-t^4}}{t^2} &= \frac{1}{t^2} \left[ 1 - \sum_{n=0}^{\infty} \frac{(-1)^n t^{4n}}{n!} \right] = \frac{1}{t^2} \sum_{n=1}^{\infty} \frac{(-1)^{n+1} t^{4n}}{n!} \\ &= \sum_{n=1}^{\infty} \frac{(-1)^{n+1} t^{4n-2}}{n!} \\ \Rightarrow f(x) &= \sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n!} \int_0^x t^{4n-2} dt = \sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n!} \left( \frac{t^{4n-1}}{4n-1} \right) \Big|_0^x \\ &= \sum_{n=1}^{\infty} \frac{(-1)^{n+1} x^{4n-1}}{n! (4n-1)} \\ &= \frac{x^3}{3} - \frac{x^7}{(2!)(7)} + \frac{x^{11}}{(3!)(11)} \pm \dots \\ &= \sum_{n=0}^{\infty} \frac{(-1)^n x^{4n+3}}{(n+1)! (4n+3)} \end{aligned}$$

2.b (5 points) Give an estimate for the value of  $f(1)$  that differs from the exact value by less than 0.01.

$$\begin{aligned} f(1) &= \sum_{n=0}^{\infty} \frac{(-1)^n}{(n+1)! (4n+3)} = \frac{1}{3} - \frac{1}{(2!)(7)} + \frac{1}{(3!)(11)} - \frac{1}{(4!)(15)} \\ &= \frac{1}{3} - \frac{1}{14} + \frac{1}{66} - \frac{1}{24 \times 15} \pm \dots \\ &\quad \hookrightarrow \frac{1}{360} < \frac{1}{100} \end{aligned}$$

$$\begin{aligned} \Rightarrow f(1) &\approx \frac{1}{3} - \frac{1}{14} + \frac{1}{66} = \frac{7 \times 22 - 33 + 7}{7 \times 66} = \frac{154 - 26}{7 \times 66} \\ &= \frac{128}{7 \times 66} = \frac{64}{7 \times 33} = \frac{64}{231} \end{aligned}$$

**Problem 3** Let  $V$  be a complex vector space,  $A$  and  $B$  be two nonempty subsets of  $V$ , and  $C$  be a subset of  $V$  whose elements are of the form  $a+b$  for some  $a \in A$  and  $b \in B$ , i.e.,

$$C := \{a+b \mid a \in A, b \in B\}.$$

**3.a** (5 points) Show that  $C$  is a subset of the span of  $A \cup B$ , i.e.,  $C \subseteq \langle A \cup B \rangle$ .

$$\forall c \in C, \exists a \in A, b \in B, c = a + b$$

$$\Downarrow \qquad \Downarrow \\ a \in A \cup B \qquad b \in A \cup B$$

$$A \cup B \subseteq \langle A \cup B \rangle \Rightarrow a, b \in \langle A \cup B \rangle \rightarrow a+b \in \langle A \cup B \rangle$$

*(Because  $\langle A \cup B \rangle$  is a subspace of  $V$ )*

$$\Rightarrow c \in \langle A \cup B \rangle \Rightarrow C \subseteq \langle A \cup B \rangle.$$

**3.b** (5 points) Show that if  $A$  and  $B$  are subspaces of  $V$ , then  $C$  is also a subspace of  $V$ .

$$1) A \text{ & } B \text{ are subspaces} \Rightarrow 0 \in A \Rightarrow 0 \in B \Rightarrow$$

$$0 = 0+0 \in C \Rightarrow 0 \in C$$

$$2) \forall c_1, c_2 \in C \quad \forall \alpha_1, \alpha_2 \in \mathbb{C}$$

$$\begin{matrix} \Downarrow & \Downarrow \\ \exists a_1, a_2 \in A, \exists b_1, b_2 \in B, & c_1 = a_1 + b_1, \\ & c_2 = a_2 + b_2 \end{matrix}$$

$$\Rightarrow \alpha_1 c_1 + \alpha_2 c_2 = \alpha_1(a_1 + b_1) + \alpha_2(a_2 + b_2)$$

$$= \alpha_1 a_1 + \alpha_2 a_2 + \alpha_1 b_1 + \alpha_2 b_2$$

$$\begin{matrix} A \text{ is a subspace} \Rightarrow \alpha_1 a_1 + \alpha_2 a_2 \in A \\ a_1, a_2 \in A \end{matrix}$$

$$\begin{matrix} B \text{ is a subspace} \Rightarrow \alpha_1 b_1 + \alpha_2 b_2 \in B \\ b_1, b_2 \in B \end{matrix}$$

$$\alpha_1 c_1 + \alpha_2 c_2 \in C$$

① & ②  $\Rightarrow C$  is a subspace of  $V$ .

**Problem 4** Let  $\mathfrak{M}(2, 2; \mathbb{R})$  be the vector space of  $2 \times 2$  real matrices and  $L : \mathfrak{M}(2, 2; \mathbb{R}) \rightarrow \mathfrak{M}(2, 2; \mathbb{R})$  be the function defined on  $\mathfrak{M}(2, 2; \mathbb{R})$  according to:  $\forall M \in \mathfrak{M}(2, 2; \mathbb{R}), L(M) := M^T$ , where  $M^T$  stands for the transpose of  $M$ , i.e., if  $M = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ , then  $L(M) = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$ .

4.a (5 points) Show that  $L$  is a linear operator.

$$1) \text{Dom}(L) = \mathfrak{M}(2, 2; \mathbb{R}) \text{ which is a subspace of } \mathfrak{M}(2, 2; \mathbb{R})$$

$$2) \forall M_1 := \begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix}, M_2 := \begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix} \in \mathfrak{M}(2, 2; \mathbb{R})$$

$$\begin{aligned} \forall \alpha_1, \alpha_2 \in \mathbb{R} & \quad \begin{bmatrix} \alpha_1 a_1 + \alpha_2 a_2 & \alpha_1 b_1 + \alpha_2 b_2 \\ \alpha_1 c_1 + \alpha_2 c_2 & \alpha_1 d_1 + \alpha_2 d_2 \end{bmatrix}^T \\ L(\alpha_1 M_1 + \alpha_2 M_2) &= \begin{bmatrix} \alpha_1 a_1 + \alpha_2 a_2 & \alpha_1 b_1 + \alpha_2 b_2 \\ \alpha_1 c_1 + \alpha_2 c_2 & \alpha_1 d_1 + \alpha_2 d_2 \end{bmatrix}^T = \alpha_1 \begin{bmatrix} a_1 & c_1 \\ b_1 & d_1 \end{bmatrix}^T + \alpha_2 \begin{bmatrix} a_2 & c_2 \\ b_2 & d_2 \end{bmatrix}^T \\ &= \alpha_1 M_1^T + \alpha_2 M_2^T = \alpha_1 L(M_1) + \alpha_2 L(M_2) \end{aligned}$$

① & ②  $\Rightarrow L$  is a linear operator.

4.b (5 points) Determine the null space of  $L$ .

$$\begin{aligned} \forall M \in \text{Nul}(L) & \quad L(M) = \emptyset \\ \begin{bmatrix} a & b \\ c & d \end{bmatrix} \subseteq \begin{bmatrix} a & c \\ b & d \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} & \Rightarrow a = c = b = d = 0 \\ \Rightarrow M = \emptyset & \Rightarrow \text{Nul}(L) = \{\emptyset\}. \end{aligned}$$

4.c (5 points) Determine if  $L$  is an isomorphism. Justify your response.

Because  $\text{Nul}(L) = \{\emptyset\}$ ,  $L$  is  $1 \rightarrow 1 : \mathfrak{M}(2, 2; \mathbb{R})$  is finite-dimensional and  $L$  is everywhere-defn'  $\hookrightarrow L$  is onto  $\hookrightarrow L$  is an isomorphism.

4.d (5 points) Let  $B := \{\mathbf{E}^{(1)}, \mathbf{E}^{(2)}, \mathbf{E}^{(3)}, \mathbf{E}^{(4)}\}$  be the standard basis of  $\mathfrak{M}(2, 2; \mathbb{R})$ , i.e.,

$$\mathbf{E}^{(1)} := \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \quad \mathbf{E}^{(2)} := \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \quad \mathbf{E}^{(3)} := \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \quad \mathbf{E}^{(4)} := \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}.$$

Find the matrix representation of  $L$  in  $B$ .

$$L(\mathbf{E}^{(1)}) = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \mathbf{E}^{(1)}$$

$$L(\mathbf{E}^{(2)}) = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} = \mathbf{E}^{(3)}$$

$$L(\mathbf{E}^{(3)}) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \mathbf{E}^{(2)}$$

$$L(\mathbf{E}^{(4)}) = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \mathbf{E}^{(4)}$$

□

The matrix representation of  $L$  in  $B$   
is:

$$L = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

**Problem 5** (10 points) Use the method of Gaussian elimination to determine the value(s) of  $\alpha$  for which the following system of equations has one or more solutions and find the general form of its solution for this value(s) of  $\alpha$ .

$$x - 2iy + 3z = \alpha$$

$$x - 8iy + 2z = 6$$

$$x + 4iy + 4z = 6$$

$$\left[ \begin{array}{ccc|c} 1 & -2i & 3 & \alpha \\ 1 & -8i & 2 & 6 \\ 1 & 4i & 4 & 6 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & -2i & 3 & \alpha \\ 0 & -6i & -1 & 6-\alpha \\ 0 & 6i & 1 & 6-\alpha \end{array} \right]$$

$$\rightarrow \left[ \begin{array}{ccc|c} 1 & -2i & 3 & \alpha \\ 0 & -6i & -1 & 6-\alpha \\ 0 & 0 & 0 & 2(6-\alpha) \end{array} \right]$$

So the system has solutions iff  $\boxed{\alpha = 6}$ .

In this case we find

$$\left[ \begin{array}{ccc|c} 1 & -2i & 3 & 6 \\ 0 & -6i & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

This corresponds to

$$x - 2iy + 3z = 6$$

$$-6iy - z = 0 \Rightarrow y = \frac{z}{-6i} = \frac{iz}{6}$$

$$0 = 0$$

$$x - 2i\left(\frac{iz}{6}\right) + 3z = 6$$

$$x + \frac{2z}{3} + 3z = 6$$

$$\Rightarrow x = 6 - \left(3z + \frac{2z}{3}\right)$$

$$y = \frac{iz}{6}$$

$z$  is an arbitrary complex number  $\hookrightarrow$  the system has only many solutions.

**Problem 6** Let  $M$  be an  $n \times n$  matrix,  $I$  be the  $n \times n$  identity matrix, and  $\lambda$  be a complex number.

6.a (5 points) Show that if  $\lambda$  is an eigenvalue of  $M$ , then  $\det(M - \lambda I) = 0$ .

$$\exists \mathbf{a} \in \mathbb{C}^n, M\mathbf{a} = \lambda \mathbf{a} \Rightarrow (M - \lambda I)\mathbf{a} = \mathbf{0}$$

$\mathbf{a} \neq \mathbf{0}$

if  $\det(M - \lambda I) \neq 0 \Rightarrow M - \lambda I$  is invertible

$$(M - \lambda \mathbf{a})^{-1}(M - \lambda I)\mathbf{a} = (M - \lambda I)^{-1}\mathbf{0}$$

$\mathbf{a} = \mathbf{0}$  which is a contradiction  $\Rightarrow \det(M - \lambda I)$

!!  
 $\mathbf{0}$ .

6.b (5 points) Show that if  $\det(M - \lambda I) = 0$ , then  $\lambda$  is an eigenvalue of  $M$ .

Let  $M : \mathbb{C}^n \rightarrow \mathbb{C}^n$  be the linear op defined by  
 $M \mathbf{x} := M \mathbf{x}$ . If  $\det(M - \lambda I) = 0$ ,  $M - \lambda I$  does not have an inverse  $\hookrightarrow M - \lambda I : \mathbb{C}^n \rightarrow \mathbb{C}^n$   
 is not invertible

Identity operator:  $\mathbb{C} \oplus \mathbb{C}$

$$\text{Nul}(M - \lambda I) \neq \{\mathbf{0}\} \Rightarrow \exists \mathbf{a} \in \mathbb{C}^n, \underset{\mathbf{a} \neq \mathbf{0}}{(M - \lambda I)\mathbf{a} = \mathbf{0}}$$

$$\text{But } (M - \lambda \mathbf{a})\mathbf{a} = M\mathbf{a} - \lambda \mathbf{a}$$

$$M\mathbf{a} - \lambda \mathbf{a} = \mathbf{0} \Rightarrow M\mathbf{a} = \lambda \mathbf{a}$$

!!

$\lambda$  is an eigenvalue of  $M$ .

6.c (5 points) Show that every eigenvalue of  $M$  is also an eigenvalue of the transpose of  $M$ .

let  $\alpha$  be an eigenvalue of  $M \Rightarrow \det(M - \alpha I) = 0$

$$\Rightarrow \det((M - \alpha I)^T) = 0 \Rightarrow \det(M^T - \alpha I^T) = 0$$

$\Rightarrow \det(M^T - \alpha I) = 0 \Rightarrow \alpha$  is an eigenvalue of  $M^T$ .

**Problem 7** (10 points) Let  $L : V \rightarrow V$  be a linear operator acting in  $V$  and having three distinct eigenvalues  $\lambda_1, \lambda_2$ , and  $\lambda_3$ . Suppose that  $v_1, v_2$ , and  $v_3$  are eigenvectors of  $L$  with eigenvalues  $\lambda_1, \lambda_2$ , and  $\lambda_3$ , respectively. Prove that  $\{v_1, v_2, v_3\}$  is a linearly-independent subset of  $V$ .

$$L v_1 = \lambda_1 v_1, \quad L v_2 = \lambda_2 v_2, \quad L v_3 = \lambda_3 v_3$$

Let  $\alpha_1, \alpha_2, \alpha_3 \in \mathbb{F}$  such that

$$\alpha_1 v_1 + \alpha_2 v_2 + \alpha_3 v_3 = 0 \quad (\text{I})$$

$$\text{Applying } L - \lambda_1 I \hookrightarrow (L - \lambda_1 I)(\alpha_1 v_1 + \alpha_2 v_2 + \alpha_3 v_3) = 0$$

$$\Rightarrow (L - \lambda_1 I)\alpha_1 v_1 + (L - \lambda_1 I)\alpha_2 v_2 + (L - \lambda_1 I)\alpha_3 v_3 = 0$$

$$\Rightarrow \underbrace{\alpha_1 (L - \lambda_1 I)v_1}_{\lambda_1 v_1 - \lambda_1 v_1} + \underbrace{\alpha_2 (L - \lambda_1 I)v_2}_{\lambda_2 v_2 - \lambda_1 v_2} + \underbrace{\alpha_3 (L - \lambda_1 I)v_3}_{\lambda_3 v_3 - \lambda_1 v_3} = 0$$

$$\Rightarrow \cancel{\lambda_1 v_1 - \lambda_1 v_1} = 0 \quad \cancel{\lambda_2 v_2 - \lambda_1 v_2} \quad \cancel{\lambda_3 v_3 - \lambda_1 v_3}$$

$$\quad \quad \quad \cancel{(\lambda_2 - \lambda_1)v_2} \quad \cancel{(\lambda_3 - \lambda_1)v_3}$$

$$\Rightarrow \alpha_2 (\lambda_2 - \lambda_1) v_2 + \alpha_3 (\lambda_3 - \lambda_1) v_3 = 0 \quad (\text{II})$$

$$\text{Applying } L - \lambda_2 I \hookrightarrow (L - \lambda_2 I) [\alpha_2 (\lambda_2 - \lambda_1) v_2 + \alpha_3 (\lambda_3 - \lambda_1) v_3] = 0$$

$$\Rightarrow \underbrace{\alpha_2 (\lambda_2 - \lambda_1) (L - \lambda_2 I) v_2}_{\lambda_2 v_2 - \lambda_2 v_2} + \underbrace{\alpha_3 (\lambda_3 - \lambda_1) (L - \lambda_2 I) v_3}_{\lambda_3 v_3 - \lambda_2 v_3} = 0$$

$$\quad \quad \quad \cancel{\lambda_2 v_2 - \lambda_2 v_2} = 0 \quad \quad \quad \cancel{\lambda_3 v_3 - \lambda_2 v_3}$$

$$\quad \quad \quad \cancel{(\lambda_3 - \lambda_2)v_3}$$

$$\Rightarrow \alpha_3 (\lambda_3 - \lambda_1) (\lambda_3 - \lambda_2) v_3 = 0$$

$$v_3 \neq 0, \quad \lambda_3 - \lambda_1 \neq 0, \quad \lambda_3 - \lambda_2 \neq 0 \quad \hookrightarrow \boxed{\alpha_3 = 0} \quad (\text{IV})$$

$$\text{I \& II} \Rightarrow \alpha_2 (\lambda_2 - \lambda_1) v_2 = 0 \quad \hookrightarrow \boxed{\alpha_2 = 0} \quad (\text{V})$$

$$\quad \quad \quad (\lambda_2 - \lambda_1) \neq 0, \quad v_2 \neq 0$$

$$\text{I \& III \& IV} \Rightarrow \alpha_1 v_1 = 0 \quad \hookrightarrow \boxed{\alpha_1 = 0}$$

$$\quad \quad \quad v_1 \neq 0$$

So  $\{v_1, v_2, v_3\}$  is linearly-independent.

**Problem 8** Let  $M := \begin{bmatrix} 1 & -\alpha \\ 0 & 2+\alpha \end{bmatrix}$  where  $\alpha$  is a real parameter.

8.a (10 points) Solve the eigenvalue problem for  $M$ , i.e., find its eigenvalues and the general form of the corresponding eigenvectors.

$$A_1 := \begin{bmatrix} 1-\lambda & -\alpha \\ 0 & 2+\alpha-\lambda \end{bmatrix} \quad \text{det } A_1 = 0$$

$$(1-\lambda)(2+\alpha-\lambda) = 0 \Rightarrow \begin{cases} \lambda = 1 \\ \lambda = 2+\alpha \end{cases}$$

For  $\lambda := \lambda_1 = 1$ ,  $A_1 a_{11} = 0 \Rightarrow \begin{bmatrix} 0 & -\alpha \\ 0 & 1+\alpha \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \beta_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$$\begin{aligned} \Rightarrow -\alpha \beta_1 &= 0 \quad \boxed{\beta_1 = 0} \\ (1+\alpha)\beta_1 &= 0 \end{aligned}$$

$$\Rightarrow a_{11} = \begin{bmatrix} \alpha_1 \\ 0 \end{bmatrix} = \alpha_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

For  $\lambda := \lambda_2 = 2+\alpha$ ,  $A_2 a_{12} = 0 \Rightarrow \begin{bmatrix} -1-\alpha & -\alpha \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \alpha_2 \\ \beta_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$$\Rightarrow -(1+\alpha)\alpha_2 - \alpha \beta_2 = 0$$

$$\Rightarrow \alpha \beta_2 = -(1+\alpha)\alpha_2$$

$$\text{If } \alpha \neq 0 \quad \hookrightarrow \quad \beta_2 = -(1+\frac{1}{\alpha})\alpha_2 \Rightarrow a_{12} = \begin{bmatrix} \alpha_2 \\ -(1+\frac{1}{\alpha})\alpha_2 \end{bmatrix}$$

$$\text{If } \alpha = 0 \quad \hookrightarrow \quad \alpha_2 = 0 \Rightarrow a_{12} = \begin{bmatrix} 0 \\ \beta_2 \end{bmatrix} = \beta_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

8.b (05 points) Find all values of  $\alpha$  such that  $M$  is not diagonalizable.

For  $M$  to be non-diagonalizable  $a_{11}$  &  $a_{12}$  must be proportional so that there is not basis of  $\mathbb{C}^2$  consisting of the eigenvectors of  $M$ . This does not happen for  $\alpha = 0$ .

It happens for  $\alpha \neq 0$  if

$$\alpha_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \alpha \alpha_2 \begin{bmatrix} 1 \\ -(1+\frac{1}{\alpha}) \end{bmatrix} \Leftrightarrow 1 + \frac{1}{\alpha} = 0$$

$$\alpha = -1$$